

# Chapter 2

## THE MATHEMATICS OF OPTIMIZATION

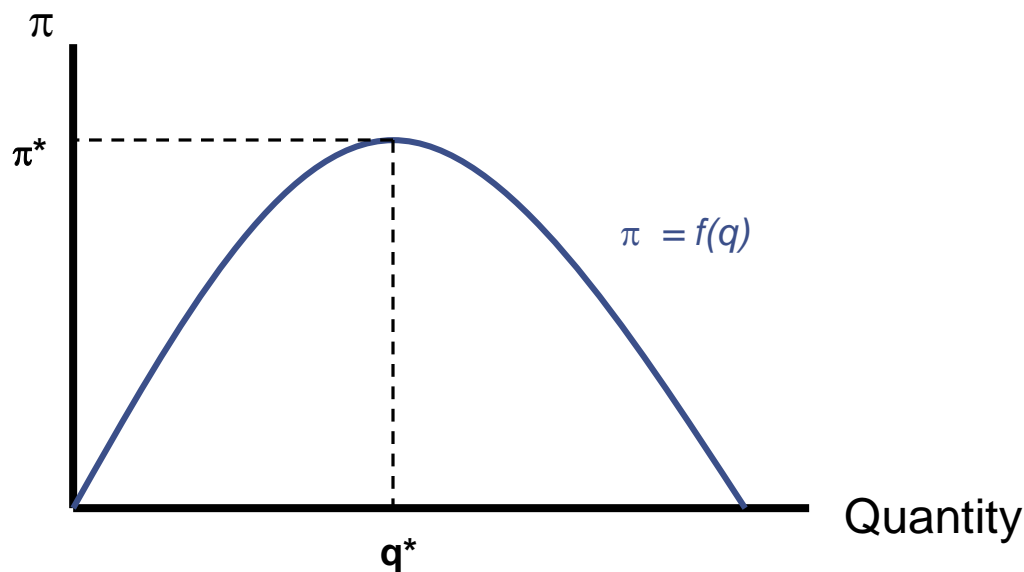
# The Mathematics of Optimization

- Many economic theories begin with the assumption that an economic agent is seeking to find the optimal value of some function
  - consumers seek to maximize utility
  - firms seek to maximize profit
- This chapter introduces the mathematics common to these problems

# Maximization of a Function of One Variable

- Simple example: Manager of a firm wishes to maximize profits

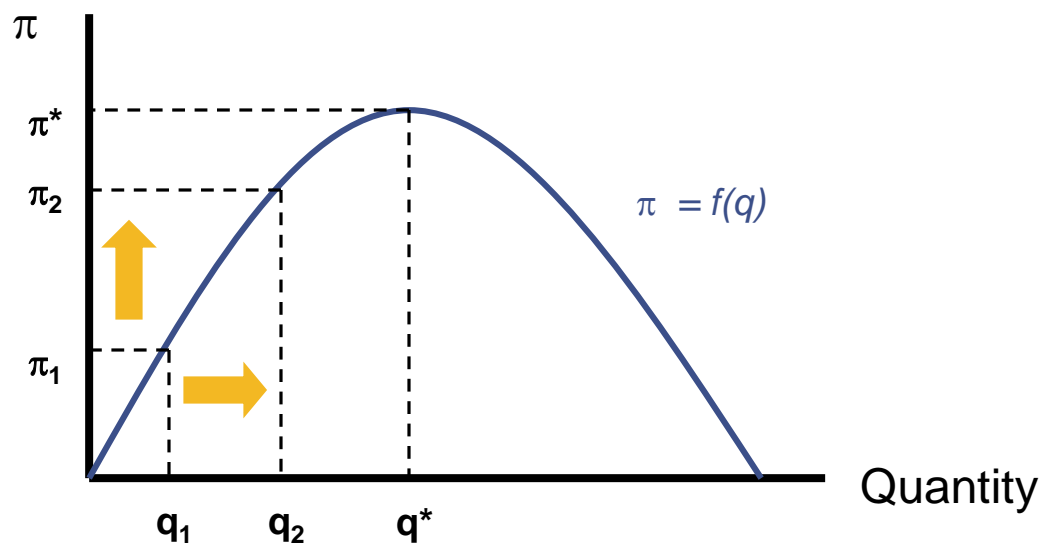
$$\pi = f(q)$$



Maximum profits of  $\pi^*$  occur at  $q^*$

# Maximization of a Function of One Variable

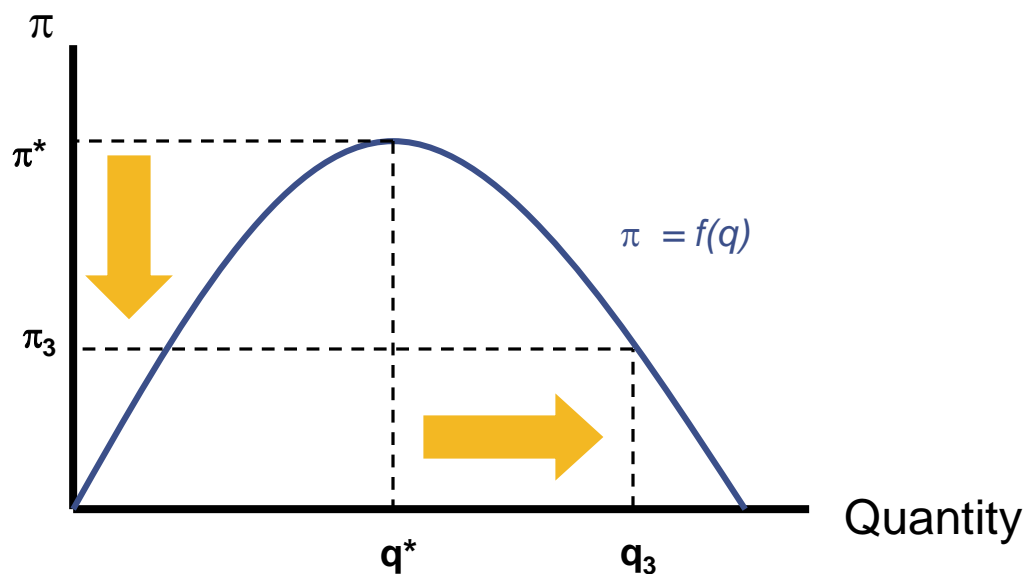
- The manager will likely try to vary  $q$  to see where the maximum profit occurs
  - an increase from  $q_1$  to  $q_2$  leads to a rise in  $\pi$



$$\frac{\Delta \pi}{\Delta q} > 0$$

# Maximization of a Function of One Variable

- If output is increased beyond  $q^*$ , profit will decline
  - an increase from  $q^*$  to  $q_3$  leads to a drop in  $\pi$



$$\frac{\Delta\pi}{\Delta q} < 0$$

# Derivatives(导数)

- The derivative of  $\pi = f(q)$  is the limit of  $\Delta\pi/\Delta q$  for very small changes in  $q$

$$\frac{d\pi}{dq} = \frac{df}{dq} = \lim_{h \rightarrow 0} \frac{f(q_1 + h) - f(q_1)}{h}$$

- The value of this ratio depends on the value of  $q_1$

# Value of a Derivative at a Point

- The evaluation of the derivative at the point  $q = q_1$  can be denoted

$$\left. \frac{d\pi}{dq} \right|_{q=q_1}$$

- In our previous example,

$$\left. \frac{d\pi}{dq} \right|_{q=q_1} > 0$$

$$\left. \frac{d\pi}{dq} \right|_{q=q_3} < 0$$

$$\left. \frac{d\pi}{dq} \right|_{q=q^*} = 0$$

# First Order Condition (一阶条件) for a Maximum

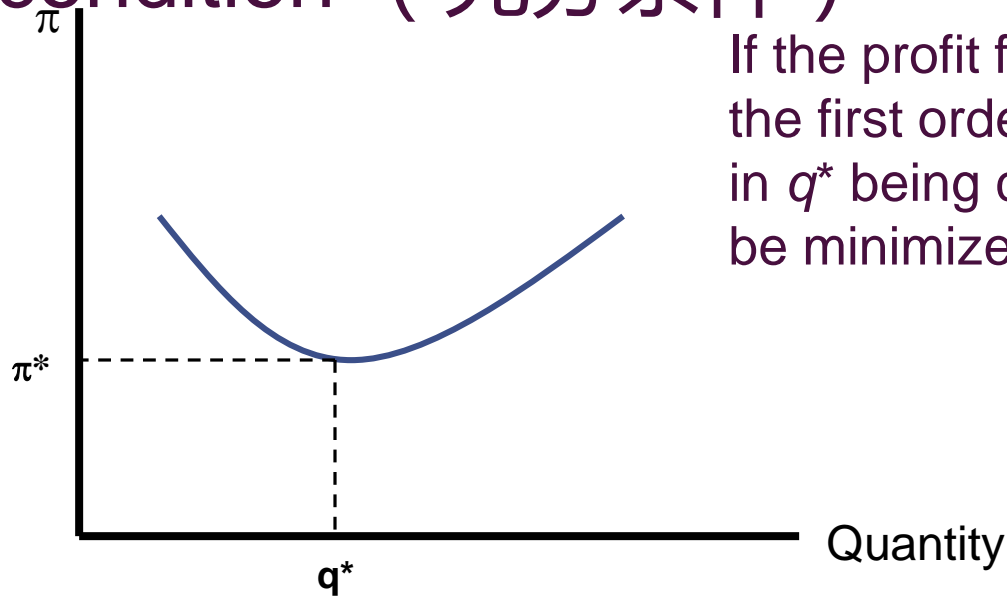
- For a function of one variable to attain its maximum value at some point, the derivative at that point must be zero

$$\left. \frac{df}{dq} \right|_{q=q^*} = 0$$



# Second Order Conditions

- The first order condition ( $d\pi/dq$ ) is a necessary condition ( 必要条件 ) for a maximum, but it is not a sufficient condition ( 充分条件 )



If the profit function was u-shaped, the first order condition would result in  $q^*$  being chosen and  $\pi$  would be minimized

# Second Order Conditions

- This must mean that, in order for  $q^*$  to be the optimum,

$$\frac{d\pi}{dq} > 0 \text{ for } q < q^* \quad \text{and} \quad \frac{d\pi}{dq} < 0 \text{ for } q > q^*$$

- Therefore, at  $q^*$ ,  $d\pi/dq$  must be decreasing

# Second Derivatives

- The derivative of a derivative is called a second derivative (二阶导数)
- The second derivative can be denoted by

$$\frac{d^2\pi}{dq^2} \text{ or } \frac{d^2f}{dq^2} \text{ or } f''(q)$$

# Second Order Condition

- The second order condition to represent a (local) maximum is

$$\left. \frac{d^2 \pi}{dq^2} \right|_{q=q^*} = f''(q) \Big|_{q=q^*} < 0$$

# Rules for Finding Derivatives

1. If  $b$  is a constant, then  $\frac{db}{dx} = 0$

2. If  $b$  is a constant, then  $\frac{d[bf(x)]}{dx} = bf'(x)$

3. If  $b$  is constant, then  $\frac{dx^b}{dx} = bx^{b-1}$

4.  $\frac{d \ln x}{dx} = \frac{1}{x}$

# Rules for Finding Derivatives

5.  $\frac{da^x}{dx} = a^x \ln a$  for any constant  $a$

– a special case of this rule is  $de^x/dx = e^x$

# Rules for Finding Derivatives

- Suppose that  $f(x)$  and  $g(x)$  are two functions of  $x$  and  $f'(x)$  and  $g'(x)$  exist
- Then

$$6. \frac{d[f(x) + g(x)]}{dx} = f'(x) + g'(x)$$

$$7. \frac{d[f(x) \cdot g(x)]}{dx} = f(x)g'(x) + f'(x)g(x)$$

# Rules for Finding Derivatives

$$8. \frac{d\left(\frac{f(x)}{g(x)}\right)}{dx} = \frac{f'(x)g(x) - f(x)g'(x)}{[g(x)]^2}$$

provided that  $g(x) \neq 0$



# Rules for Finding Derivatives

- If  $y = f(x)$  and  $x = g(z)$  and if both  $f'(x)$  and  $g'(z)$  exist, then:

$$9. \frac{dy}{dz} = \frac{dy}{dx} \cdot \frac{dx}{dz} = \frac{df}{dx} \cdot \frac{dg}{dz}$$

- This is called the chain rule ( 链式法则 ). The chain rule allows us to study how one variable ( $z$ ) affects another variable ( $y$ ) through its influence on some intermediate variable ( $x$ )

# Rules for Finding Derivatives

- Some examples of the chain rule include

$$10. \frac{de^{ax}}{dx} = \frac{de^{ax}}{d(ax)} \cdot \frac{d(ax)}{dx} = e^{ax} \cdot a = ae^{ax}$$

$$11. \frac{d[\ln(ax)]}{dx} = \frac{d[\ln(ax)]}{d(ax)} \cdot \frac{d(ax)}{dx} = \ln(ax) \cdot a = a \ln(ax)$$

$$12. \frac{d[\ln(x^2)]}{dx} = \frac{d[\ln(x^2)]}{d(x^2)} \cdot \frac{d(x^2)}{dx} = \frac{1}{x^2} \cdot 2x = \frac{2}{x}$$

# Example of Profit Maximization

- Suppose that the relationship between profit and output is

$$\pi = 1,000q - 5q^2$$

- The first order condition for a maximum is

$$d\pi/dq = 1,000 - 10q = 0$$

$$q^* = 100$$

- Since the second derivative is always -10,  $q = 100$  is a global maximum

# Functions of Several Variables

- Most goals of economic agents depend on several variables
  - trade-offs ( 权衡 , 两相取舍 ) must be made
- The dependence of one variable ( $y$ ) on a series of other variables ( $x_1, x_2, \dots, x_n$ ) is denoted by
$$y = f(x_1, x_2, \dots, x_n)$$

# Partial Derivatives ( 偏导数 )

- The partial derivative of  $y$  with respect to  $x_1$  is denoted by

$$\frac{\partial y}{\partial x_1} \text{ or } \frac{\partial f}{\partial x_1} \text{ or } f_{x_1} \text{ or } f_1$$

- It is understood that in calculating the partial derivative, all of the other  $x$ 's are held constant

# Partial Derivatives

- A more formal definition of the partial derivative is

$$\left. \frac{\partial f}{\partial x_1} \right|_{\bar{x}_2, \dots, \bar{x}_n} = \lim_{h \rightarrow 0} \frac{f(x_1 + h, \bar{x}_2, \dots, \bar{x}_n) - f(x_1, \bar{x}_2, \dots, \bar{x}_n)}{h}$$

# Calculating Partial Derivatives

1. If  $y = f(x_1, x_2) = ax_1^2 + bx_1x_2 + cx_2^2$ , then

$$\frac{\partial f}{\partial x_1} = f_1 = 2ax_1 + bx_2 \quad \text{and}$$

$$\frac{\partial f}{\partial x_2} = f_2 = bx_1 + 2cx_2$$

2. If  $y = f(x_1, x_2) = e^{ax_1 + bx_2}$ , then

$$\frac{\partial f}{\partial x_1} = f_1 = ae^{ax_1 + bx_2} \quad \text{and} \quad \frac{\partial f}{\partial x_2} = f_2 = be^{ax_1 + bx_2}$$

# Calculating Partial Derivatives

3. If  $y = f(x_1, x_2) = a \ln x_1 + b \ln x_2$ , then

$$\frac{\partial f}{\partial x_1} = f_1 = \frac{a}{x_1} \quad \text{and} \quad \frac{\partial f}{\partial x_2} = f_2 = \frac{b}{x_2}$$



# Partial Derivatives

- Partial derivatives are the mathematical expression of the *ceteris paribus* assumption
  - show how changes in one variable affect some outcome when other influences are held constant

# Partial Derivatives

- We must be concerned with how variables are measured
  - if  $q$  represents the quantity of gasoline demanded (measured in billions of gallons) and  $p$  represents the price in dollars per gallon, then  $\partial q/\partial p$  will measure the change in demand (in billions of gallons per year) for a dollar per gallon change in price

# Elasticity (弹性)

- Elasticities measure the proportional effect of a change in one variable on another
  - unit free (与单位无关)
- The elasticity of  $y$  with respect to  $x$  is

$$e_{y,x} = \frac{\frac{\Delta y}{y}}{\frac{\Delta x}{x}} = \frac{\Delta y}{\Delta x} \cdot \frac{x}{y} = \frac{\partial y}{\partial x} \cdot \frac{x}{y}$$

# Elasticity and Functional Form

- Suppose that

$$y = a + bx + \text{other terms}$$

- In this case,

$$e_{y,x} = \frac{\partial y}{\partial x} \cdot \frac{x}{y} = b \cdot \frac{x}{y} = b \cdot \frac{x}{a + bx + \dots}$$

- $e_{y,x}$  is not constant
  - it is important to note the point at which the elasticity is to be computed

# Elasticity and Functional Form

- Suppose that

$$y = ax^b$$

- In this case,

$$e_{y,x} = \frac{\partial y}{\partial x} \cdot \frac{x}{y} = abx^{b-1} \cdot \frac{x}{ax^b} = b$$

# Elasticity and Functional Form

- Suppose that

$$\ln y = \ln a + b \ln x$$

- In this case,

$$e_{y,x} = \frac{\partial y}{\partial x} \cdot \frac{x}{y} = b \cdot \frac{\partial \ln y}{\partial \ln x}$$

- Elasticities can be calculated through logarithmic differentiation

# Second-Order Partial Derivatives

- The partial derivative of a partial derivative is called a second-order partial derivative

$$\frac{\partial(\partial f / \partial x_i)}{\partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i} = f_{ij}$$

# Young's Theorem

- Under general conditions, the order in which partial differentiation is conducted to evaluate second-order partial derivatives does not matter

$$f_{ij} = f_{ji}$$



# Use of Second-Order Partial

- Second-order partials play an important role in many economic theories
- One of the most important is a variable's own second-order partial,  $f_{ii}$ 
  - shows how the marginal influence of  $x_i$  on  $y(\partial y/\partial x_i)$  changes as the value of  $x_i$  increases
  - a value of  $f_{ii} < 0$  indicates diminishing marginal effectiveness

# Total Differential

- Suppose that  $y = f(x_1, x_2, \dots, x_n)$
- If all  $x$ 's are varied by a small amount, the total effect on  $y$  will be

$$dy = \frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial x_2} dx_2 + \dots + \frac{\partial f}{\partial x_n} dx_n$$

$$dy = f_1 dx_1 + f_2 dx_2 + \dots + f_n dx_n$$

# First-Order Condition for a Maximum (or Minimum)

- A necessary condition for a maximum (or minimum) of the function  $f(x_1, x_2, \dots, x_n)$  is that  $dy = 0$  for any combination of small changes in the  $x$ 's
- The only way for this to be true is if

$$f_1 = f_2 = \dots = f_n = 0$$

- A point where this condition holds is called a critical point (奇点, 零点)

# Finding a Maximum

- Suppose that  $y$  is a function of  $x_1$  and  $x_2$

$$y = - (x_1 - 1)^2 - (x_2 - 2)^2 + 10$$

$$y = - x_1^2 + 2x_1 - x_2^2 + 4x_2 + 5$$

- First-order conditions imply that

$$\frac{\partial y}{\partial x_1} = -2x_1 + 2 = 0$$

OR

$$x_1^* = 1$$

$$x_2^* = 2$$

$$\frac{\partial y}{\partial x_2} = -2x_2 + 4 = 0$$

# Production Possibility Frontier

- Earlier example:  $2x^2 + y^2 = 225$
- Can be rewritten:  $f(x,y) = 2x^2 + y^2 - 225 = 0$
- Because  $f_x = 4x$  and  $f_y = 2y$ , the opportunity cost trade-off between  $x$  and  $y$  is

$$\frac{dy}{dx} = \frac{-f_x}{f_y} = \frac{-4x}{2y} = \frac{-2x}{y}$$

# Implicit Function Theorem ( 隐函数定理 )

- It may not always be possible to solve implicit functions of the form  $g(x,y)=0$  for unique explicit functions of the form  $y = f(x)$ 
  - mathematicians have derived the necessary conditions
  - in many economic applications, these conditions are the same as the second-order conditions for a maximum (or minimum)

# The Envelope Theorem (包络定理)

- The envelope theorem concerns how the optimal value for a particular function changes when a parameter of the function changes
- This is easiest to see by using an example

# The Envelope Theorem

- Suppose that  $y$  is a function of  $x$

$$y = -x^2 + ax$$

- For different values of  $a$ , this function represents a family of inverted parabolas ( 翻转抛物线 )
- If  $a$  is assigned a specific value, then  $y$  becomes a function of  $x$  only and the value of  $x$  that maximizes  $y$  can be calculated

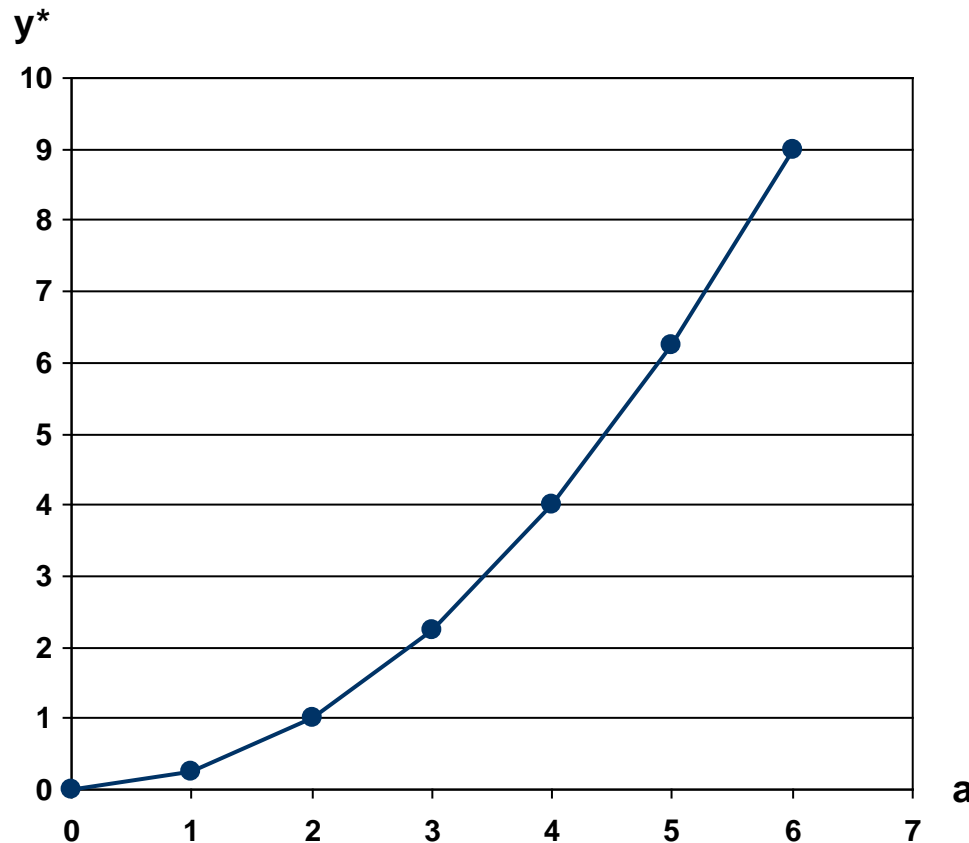


# The Envelope Theorem

Optimal Values of  $x$  and  $y$  for alternative values of  $a$

<u>Value of <math>a</math></u>	<u>Value of <math>x^*</math></u>	<u>Value of <math>y^*</math></u>
0	0	0
1	1/2	1/4
2	1	1
3	3/2	9/4
4	2	4
5	5/2	25/4
6	3	9

# The Envelope Theorem



**As  $a$  increases,  
the maximal value  
for  $y$  ( $y^*$ ) increases**

**The relationship  
between  $a$  and  $y$   
is quadratic**

# The Envelope Theorem

- Suppose we are interested in how  $y^*$  changes as  $a$  changes
- There are two ways we can do this
  - calculate the slope of  $y$  directly
  - hold  $x$  constant at its optimal value and calculate  $\partial y / \partial a$  directly

# The Envelope Theorem

- To calculate the slope of the function, we must solve for the optimal value of  $x$  for any value of  $a$

$$dy/dx = -2x + a = 0$$

$$x^* = a/2$$

- Substituting, we get

$$y^* = -(x^*)^2 + a(x^*) = -(a/2)^2 + a(a/2)$$

$$y^* = -a^2/4 + a^2/2 = a^2/4$$

# The Envelope Theorem

- Therefore,

$$dy^*/da = 2a/4 = a/2 = x^*$$

- But, we can save time by using the envelope theorem
  - for small changes in  $a$ ,  $dy^*/da$  can be computed by holding  $x$  at  $x^*$  and calculating  $\partial y / \partial a$  directly from  $y$

# The Envelope Theorem

$$\partial y / \partial a = x$$

- Holding  $x = x^*$

$$\partial y / \partial a = x^* = a/2$$

- This is the same result found earlier

# The Envelope Theorem

- The envelope theorem states that the change in the optimal value of a function with respect to a parameter of that function can be found by partially differentiating the objective function while holding  $x$  (or several  $x$ 's) at its optimal value

$$\frac{dy^*}{da} = \frac{\partial y}{\partial a} \{ x = x^*(a) \}$$

# The Envelope Theorem

- The envelope theorem can be extended to the case where  $y$  is a function of several variables

$$y = f(x_1, \dots, x_n, a)$$

- Finding an optimal value for  $y$  would consist of solving  $n$  first-order equations

$$\partial y / \partial x_i = 0 \quad (i = 1, \dots, n)$$



# The Envelope Theorem

- Optimal values for these  $x$ 's would be determined that are a function of  $a$

$$x_1^* = x_1^*(a)$$

$$x_2^* = x_2^*(a)$$

•

•

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$$x_n^* = x_n^*(a)$$

# The Envelope Theorem

- Substituting into the original objective function yields an expression for the optimal value of  $y$  ( $y^*$ )

$$y^* = f[x_1^*(a), x_2^*(a), \dots, x_n^*(a), a]$$

- Differentiating yields

$$\frac{dy^*}{da} = \frac{\partial f}{\partial x_1} \cdot \frac{dx_1}{da} + \frac{\partial f}{\partial x_2} \cdot \frac{dx_2}{da} + \dots + \frac{\partial f}{\partial x_n} \cdot \frac{dx_n}{da} + \frac{\partial f}{\partial a}$$

# The Envelope Theorem

- Because of first-order conditions, all terms except  $\partial f / \partial a$  are equal to zero if the  $x$ 's are at their optimal values
- Therefore,

$$\frac{dy^*}{da} = \frac{\partial f}{\partial a} \{ x = x^*(a) \}$$

# Constrained Maximization

- What if not all values for the  $x$ 's are feasible?
  - the values of  $x$  may all have to be positive
  - a consumer's choices are limited by the amount of purchasing power available
- One method used to solve constrained maximization problems is the Lagrangian multiplier method

# Lagrangian Multiplier Method

- Suppose that we wish to find the values of  $x_1, x_2, \dots, x_n$  that maximize

$$y = f(x_1, x_2, \dots, x_n)$$

subject to a constraint that permits only certain values of the  $x$ 's to be used

$$g(x_1, x_2, \dots, x_n) = 0$$

# Lagrangian Multiplier Method

- The Lagrangian multiplier method starts with setting up the expression

$$\mathbf{L} = f(x_1, x_2, \dots, x_n) + \lambda g(x_1, x_2, \dots, x_n)$$

where  $\lambda$  is an additional variable called a Lagrangian multiplier

- When the constraint holds,  $\mathbf{L} = f$  because  $g(x_1, x_2, \dots, x_n) = 0$

# Lagrangian Multiplier Method

- First-Order Conditions

$$\partial \mathbf{L} / \partial x_1 = f_1 + \lambda g_1 = 0$$

$$\partial \mathbf{L} / \partial x_2 = f_2 + \lambda g_2 = 0$$

⋮

$$\partial \mathbf{L} / \partial x_n = f_n + \lambda g_n = 0$$

$$\partial \mathbf{L} / \partial \lambda = g(x_1, x_2, \dots, x_n) = 0$$

# Lagrangian Multiplier Method

- The first-order conditions can generally be solved for  $x_1, x_2, \dots, x_n$  and  $\lambda$
- The solution will have two properties:
  - the  $x$ 's will obey the constraint
  - these  $x$ 's will make the value of  $L$  (and therefore  $f$ ) as large as possible



# Lagrangian Multiplier Method

- The Lagrangian multiplier ( $\lambda$ ) has an important economic interpretation
- The first-order conditions imply that

$$f_1/-g_1 = f_2/-g_2 = \dots = f_n/-g_n = \lambda$$

- the numerators above measure the marginal benefit that one more unit of  $x_i$  will have for the function  $f$
- the denominators reflect the added burden on the constraint of using more  $x_i$

# Lagrangian Multiplier Method

- At the optimal choices for the  $x$ 's, the ratio of the marginal benefit of increasing  $x_i$  to the marginal cost of increasing  $x_i$  should be the same for every  $x$
- $\lambda$  is the common cost-benefit ratio for all of the  $x$ 's

$$\lambda = \frac{\text{marginal benefit of } x_i}{\text{marginal cost of } x_i}$$

# Lagrangian Multiplier Method

- If the constraint was relaxed slightly, it would not matter which  $x$  is changed
- The Lagrangian multiplier provides a measure of how the relaxation in the constraint will affect the value of  $y$
- $\lambda$  provides a “shadow price” ( 影子价格 ) to the constraint

# Lagrangian Multiplier Method

- A high value of  $\lambda$  indicates that  $y$  could be increased substantially by relaxing the constraint
  - each  $x$  has a high cost-benefit ratio
- A low value of  $\lambda$  indicates that there is not much to be gained by relaxing the constraint
- $\lambda=0$  implies that the constraint is not binding

# Duality (对偶性)

- Any constrained maximization problem has associated with it a dual problem in constrained minimization that focuses attention on the constraints in the original problem

# Duality

- Individuals maximize utility subject to a budget constraint
  - dual problem: individuals minimize the expenditure needed to achieve a given level of utility
- Firms minimize the cost of inputs to produce a given level of output
  - dual problem: firms maximize output for a given cost of inputs purchased

# Constrained Maximization

- Suppose a farmer had a certain length of fence ( $P$ ) and wished to enclose the largest possible rectangular shape
- Let  $x$  be the length of one side
- Let  $y$  be the length of the other side
- Problem: choose  $x$  and  $y$  so as to maximize the area ( $A = x \cdot y$ ) subject to the constraint that the perimeter is fixed at  $P = 2x + 2y$

# Constrained Maximization

- Setting up the Lagrangian multiplier

$$L = x \cdot y + \lambda(P - 2x - 2y)$$

- The first-order conditions for a maximum are

$$\partial L / \partial x = y - 2\lambda = 0$$

$$\partial L / \partial y = x - 2\lambda = 0$$

$$\partial L / \partial \lambda = P - 2x - 2y = 0$$



# Constrained Maximization

- Since  $y/2 = x/2 = \lambda$ ,  $x$  must be equal to  $y$ 
  - the field should be square
  - $x$  and  $y$  should be chosen so that the ratio of marginal benefits to marginal costs should be the same
- Since  $x = y$  and  $y = 2\lambda$ , we can use the constraint to show that

$$x = y = P/4$$

$$\lambda = P/8$$

# Constrained Maximization

- Interpretation of the Lagrangian multiplier
  - if the farmer was interested in knowing how much more field could be fenced by adding an extra yard of fence,  $\lambda$  suggests that he could find out by dividing the present perimeter ( $P$ ) by 8
  - thus, the Lagrangian multiplier provides information about the implicit value of the constraint

# Constrained Maximization

- Dual problem: choose  $x$  and  $y$  to minimize the amount of fence required to surround the field

$$\text{minimize } P = 2x + 2y \text{ subject to } A = x \cdot y$$

- Setting up the Lagrangian:

$$L^D = 2x + 2y + \lambda^D(A - x \cdot y)$$

# Constrained Maximization

- First-order conditions:

$$\partial \mathbf{L}^D / \partial x = 2 - \lambda^D \cdot y = 0$$

$$\partial \mathbf{L}^D / \partial y = 2 - \lambda^D \cdot x = 0$$

$$\partial \mathbf{L}^D / \partial \lambda^D = A - x \cdot y = 0$$

- Solving, we get

$$x = y = A^{1/2}$$

- The Lagrangian multiplier  $(\lambda^D) = 2A^{-1/2}$

# Envelope Theorem & Constrained Maximization

- Suppose that we want to maximize

$$y = f(x_1, \dots, x_n; a)$$

subject to the constraint

$$g(x_1, \dots, x_n; a) = 0$$

- One way to solve would be to set up the Lagrangian expression and solve the first-order conditions

# Envelope Theorem & Constrained Maximization

- Alternatively, it can be shown that

$$dy^*/da = \partial \mathbf{L} / \partial a(x_1^*, \dots, x_n^*; a)$$

- The change in the maximal value of  $y$  that results when  $a$  changes can be found by partially differentiating  $\mathbf{L}$  and evaluating the partial derivative at the optimal point

# Inequality Constraints

- In some economic problems the constraints need not hold exactly
- For example, suppose we seek to maximize  $y = f(x_1, x_2)$  subject to

$$g(x_1, x_2) \geq 0,$$

$$x_1 \geq 0, \text{ and}$$

$$x_2 \geq 0$$

# Inequality Constraints

- One way to solve this problem is to introduce three new variables ( $a$ ,  $b$ , and  $c$ ) that convert the inequalities into equalities
- To ensure that the inequalities continue to hold, we will square these new variables to ensure that their values are positive



# Inequality Constraints

$$g(x_1, x_2) - a^2 = 0;$$

$$x_1 - b^2 = 0; \text{ and}$$

$$x_2 - c^2 = 0$$

- Any solution that obeys these three equality constraints will also obey the inequality constraints

# Inequality Constraints

- We can set up the Lagrangian

$$L = f(x_1, x_2) + \lambda_1[g(x_1, x_2) - a^2] + \lambda_2[x_1 - b^2] + \lambda_3[x_2 - c^2]$$

- This will lead to eight first-order conditions

# Inequality Constraints

$$\partial \mathbf{L} / \partial x_1 = f_1 + \lambda_1 g_1 + \lambda_2 = 0$$

$$\partial \mathbf{L} / \partial x_2 = f_1 + \lambda_1 g_2 + \lambda_3 = 0$$

$$\partial \mathbf{L} / \partial a = -2a\lambda_1 = 0$$

$$\partial \mathbf{L} / \partial b = -2b\lambda_2 = 0$$

$$\partial \mathbf{L} / \partial c = -2c\lambda_3 = 0$$

$$\partial \mathbf{L} / \partial \lambda_1 = g(x_1, x_2) - a^2 = 0$$

$$\partial \mathbf{L} / \partial \lambda_2 = x_1 - b^2 = 0$$

$$\partial \mathbf{L} / \partial \lambda_3 = x_2 - c^2 = 0$$

# Inequality Constraints

- According to the third condition, either  $a$  or  $\lambda_1 = 0$ 
  - if  $a = 0$ , the constraint  $g(x_1, x_2)$  holds exactly
  - if  $\lambda_1 = 0$ , the availability of some slackness of the constraint implies that its value to the objective function is 0
- Similar complementary slackness ( 互補 松弛 ) relationships also hold for  $x_1$  and  $x_2$

$$\partial \lambda_1 \partial \mathbf{L} / \partial \lambda_1 = 0$$

# Inequality Constraints

- These results are sometimes called Kuhn-Tucker conditions
  - they show that solutions to optimization problems involving inequality constraints will differ from similar problems involving equality constraints in rather simple ways
  - we cannot go wrong by working primarily with constraints involving equalities

# Second Order Conditions - Functions of One Variable

- Let  $y = f(x)$
- A necessary condition for a maximum is that

$$dy/dx = f'(x) = 0$$

- To ensure that the point is a maximum,  $y$  must be decreasing for movements away from it

# Second Order Conditions - Functions of One Variable


- The total differential measures the change in  $y$

$$dy = f'(x) dx$$

- To be at a maximum,  $dy$  must be decreasing for small increases in  $x$
- To see the changes in  $dy$ , we must use the second derivative of  $y$

# Second Order Conditions - Functions of One Variable

$$d^2y = \frac{d[f'(x)dx]}{dx} \cdot dx = f''(x)dx \cdot dx = f''(x)dx^2$$

- Note that  $d^2y < 0$  implies that  $f''(x)dx^2 < 0$
- Since  $dx^2$  must be positive,  $f''(x) < 0$
- This means that the function  $f$  must have a concave (  ) shape at the critical point



# Second Order Conditions - Functions of Two Variables

- Suppose that  $y = f(x_1, x_2)$
- First order conditions for a maximum are

$$\partial y / \partial x_1 = f_1 = 0$$

$$\partial y / \partial x_2 = f_2 = 0$$

- To ensure that the point is a maximum,  $y$  must diminish for movements in any direction away from the critical point

# Second Order Conditions - Functions of Two Variables

- The slope in the  $x_1$  direction ( $f_1$ ) must be diminishing at the critical point
- The slope in the  $x_2$  direction ( $f_2$ ) must be diminishing at the critical point
- But, conditions must also be placed on the cross-partial derivative ( $f_{12} = f_{21}$ ) to ensure that  $dy$  is decreasing for all movements through the critical point

# Second Order Conditions - Functions of Two Variables

- The total differential of  $y$  is given by

$$dy = f_1 dx_1 + f_2 dx_2$$

- The differential of that function is

$$d^2y = (f_{11} dx_1 + f_{12} dx_2) dx_1 + (f_{21} dx_1 + f_{22} dx_2) dx_2$$

$$d^2y = f_{11} dx_1^2 + f_{12} dx_2 dx_1 + f_{21} dx_1 dx_2 + f_{22} dx_2^2$$

- By Young's theorem,  $f_{12} = f_{21}$  and

$$d^2y = f_{11} dx_1^2 + 2f_{12} dx_1 dx_2 + f_{22} dx_2^2$$

# Second Order Conditions - Functions of Two Variables

$$d^2y = f_{11}dx_1^2 + 2f_{12}dx_1dx_2 + f_{22}dx_2^2$$

- For this equation to be unambiguously negative for any change in the x's,  $f_{11}$  and  $f_{22}$  must be negative
- If  $dx_2 = 0$ , then  $d^2y = f_{11} dx_1^2$ 
  - for  $d^2y < 0$ ,  $f_{11} < 0$
- If  $dx_1 = 0$ , then  $d^2y = f_{22} dx_2^2$ 
  - for  $d^2y < 0$ ,  $f_{22} < 0$

# Second Order Conditions - Functions of Two Variables

$$d^2y = f_{11}dx_1^2 + 2f_{12}dx_1dx_2 + f_{22}dx_2^2$$

- If neither  $dx_1$  nor  $dx_2$  is zero, then  $d^2y$  will be unambiguously negative only if

$$f_{11} f_{22} - f_{12}^2 > 0$$

- the second partial derivatives ( $f_{11}$  and  $f_{22}$ ) must be sufficiently negative so that they outweigh any possible perverse effects from the cross-partial derivatives ( $f_{12} = f_{21}$ )

# Constrained Maximization

- Suppose we want to choose  $x_1$  and  $x_2$  to maximize

$$y = f(x_1, x_2)$$

- subject to the linear constraint

$$c - b_1x_1 - b_2x_2 = 0$$

- We can set up the Lagrangian

$$L = f(x_1, x_2) + \lambda(c - b_1x_1 - b_2x_2)$$

# Constrained Maximization

- The first-order conditions are

$$f_1 - \lambda b_1 = 0$$

$$f_2 - \lambda b_2 = 0$$

$$c - b_1x_1 - b_2x_2 = 0$$

- To ensure we have a maximum, we must use the “second” total differential

$$d^2y = f_{11}dx_1^2 + 2f_{12}dx_1dx_2 + f_{22}dx_2^2$$

# Constrained Maximization

- Only the values of  $x_1$  and  $x_2$  that satisfy the constraint can be considered valid alternatives to the critical point
- Thus, we must calculate the total differential of the constraint

$$-b_1 dx_1 - b_2 dx_2 = 0$$

$$dx_2 = -(b_1/b_2)dx_1$$

- These are the allowable relative changes in  $x_1$  and  $x_2$



# Constrained Maximization

- Because the first-order conditions imply that  $f_1/f_2 = b_1/b_2$ , we can substitute and get

$$dx_2 = -(f_1/f_2) dx_1$$

- Since

$$d^2y = f_{11}dx_1^2 + 2f_{12}dx_1dx_2 + f_{22}dx_2^2$$

we can substitute for  $dx_2$  and get

$$d^2y = f_{11}dx_1^2 - 2f_{12}(f_1/f_2)dx_1^2 + f_{22}(f_1^2/f_2^2)dx_1^2$$

# Constrained Maximization

- Combining terms and rearranging

$$d^2y = f_{11} f_2^2 - 2f_{12}f_1f_2 + f_{22}f_1^2 [dx_1^2 / f_2^2]$$

- Therefore, for  $d^2y < 0$ , it must be true that

$$f_{11} f_2^2 - 2f_{12}f_1f_2 + f_{22}f_1^2 < 0$$

- This equation characterizes a set of functions termed quasi-concave (拟凹) functions

– any two points within the set can be joined by a line contained completely in the set

# Concave and Quasi-Concave Functions

- The differences between concave and quasi-concave functions can be illustrated with the function

$$y = f(x_1, x_2) = (x_1 \cdot x_2)^k$$

where the  $x$ 's take on only positive values and  $k$  can take on a variety of positive values

# Concave and Quasi-Concave Functions

- No matter what value  $k$  takes, this function is quasi-concave
- Whether or not the function is concave depends on the value of  $k$ 
  - if  $k < 0.5$ , the function is concave
  - if  $k > 0.5$ , the function is convex

# Homogeneous ( 齐次 ) Functions

- A function  $f(x_1, x_2, \dots, x_n)$  is said to be homogeneous of degree  $k$  if

$$f(tx_1, tx_2, \dots, tx_n) = t^k f(x_1, x_2, \dots, x_n)$$

- when a function is homogeneous of degree one, a doubling of all of its arguments doubles the value of the function itself
- when a function is homogeneous of degree zero, a doubling of all of its arguments leaves the value of the function unchanged

# Homogeneous Functions

- If a function is homogeneous of degree  $k$ , the partial derivatives of the function will be homogeneous of degree  $k-1$

# Euler's Theorem

- If we differentiate the definition for homogeneity with respect to the proportionality factor  $t$ , we get

$$kt^{k-1}f(x_1, \dots, x_n) = x_1 f_1(tx_1, \dots, tx_n) + \dots + x_n f_n(x_1, \dots, x_n)$$

- This relationship is called Euler's theorem

# Euler's Theorem

- Euler's theorem shows that, for homogeneous functions, there is a definite relationship between the values of the function and the values of its partial derivatives



# Homothetic ( 同位 ) Functions

- A homothetic function is one that is formed by taking a monotonic transformation of a homogeneous function
  - they do not possess the homogeneity properties of their underlying functions

# Homothetic Functions

- For both homogeneous and homothetic functions, the implicit trade-offs among the variables in the function depend only on the ratios of those variables, not on their absolute values

# Homothetic Functions

- Suppose we are examining the simple, two variable implicit function  $f(x,y) = 0$
- The implicit trade-off between  $x$  and  $y$  for a two-variable function is

$$dy/dx = -f_x/f_y$$

- If we assume  $f$  is homogeneous of degree  $k$ , its partial derivatives will be homogeneous of degree  $k-1$

# Homothetic Functions

- The implicit trade-off between  $x$  and  $y$  is

$$\frac{dy}{dx} = -\frac{t^{k-1}f_x(tx, ty)}{t^{k-1}f_y(tx, ty)} = -\frac{f_x(tx, ty)}{f_y(tx, ty)}$$

- If  $t = 1/y$ ,

$$\frac{dy}{dx} = -\frac{F' f_x\left(\frac{x}{y}, 1\right)}{F' f_y\left(\frac{x}{y}, 1\right)} = -\frac{f_x\left(\frac{x}{y}, 1\right)}{f_y\left(\frac{x}{y}, 1\right)}$$

# Homothetic Functions

- The trade-off is unaffected by the monotonic transformation and remains a function only of the ratio  $x$  to  $y$

# Important Points to Note:

- Using mathematics provides a convenient, short-hand way for economists to develop their models
  - implications of various economic assumptions can be studied in a simplified setting through the use of such mathematical tools

# Important Points to Note:

- Derivatives are often used in economics because economists are interested in how marginal changes in one variable affect another
  - partial derivatives incorporate the *ceteris paribus* assumption used in most economic models

# Important Points to Note:

- The mathematics of optimization is an important tool for the development of models that assume that economic agents rationally pursue some goal
  - the first-order condition for a maximum requires that all partial derivatives equal zero



# Important Points to Note:

- Most economic optimization problems involve constraints on the choices that agents can make
  - the first-order conditions for a maximum suggest that each activity be operated at a level at which the ratio of the marginal benefit of the activity to its marginal cost

# Important Points to Note:

- The Lagrangian multiplier is used to help solve constrained maximization problems
  - the Lagrangian multiplier can be interpreted as the implicit value (shadow price) of the constraint

# Important Points to Note:

- The implicit function theorem illustrates the dependence of the choices that result from an optimization problem on the parameters of that problem

# Important Points to Note:

- The envelope theorem examines how optimal choices will change as the problem's parameters change
- Some optimization problems may involve constraints that are inequalities rather than equalities

# Important Points to Note:

- First-order conditions are necessary but not sufficient for ensuring a maximum or minimum
  - second-order conditions that describe the curvature ( 曲度 ) of the function must be checked

# Important Points to Note:

- Certain types of functions occur in many economic problems
  - quasi-concave functions obey the second-order conditions of constrained maximum or minimum problems when the constraints are linear
  - homothetic functions have the property that implicit trade-offs among the variables depend only on the ratios of these variables